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| **Python with Robots**  **Mission 3 Lab Data Sheet – OBJ 7** | | | **Name:** | | |
| **Obj 7 Get Moving:** How far does the CodeBot move if both wheels have the same power, with a given delay? | | | | | |
| **Wheel power setting** | | **Sleep delay** | | **Distance traveled** | |
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| **Obj 8 Rotation Time:** What angle does the CodeBot turn with a given wheel power and delay? | | | | | |
| **Left Wheel power** | **Right Wheel power** | | **Sleep delay** | | **Angle and rotation (which way)** |
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| **Planning Guide:** Turn this paper over. Plan your navigation square by using a flowchart of pseudocode. | | | | | |

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